

**Multi-objective
Reinforcement Learning
for
Energy Harvesting
Wireless Sensor Nodes**

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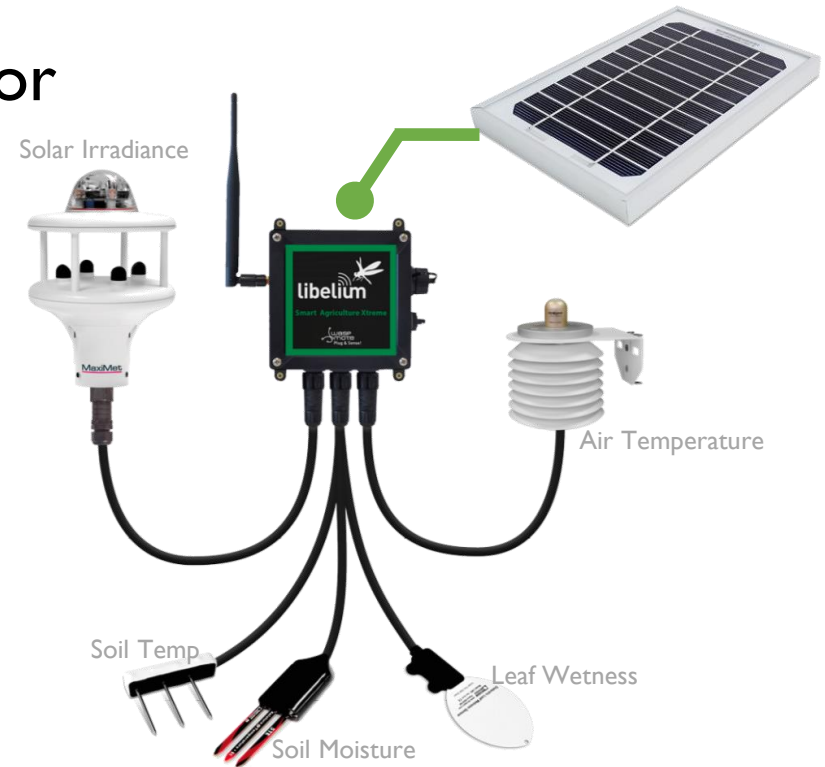
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Keio University

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The University of Tokyo

Billions of Autonomous Sensor Nodes

- Energy Harvesting Wireless Sensor Nodes (EHWSNs)

- sense, process and transmit data wirelessly
- harvest energy from the ambient environment

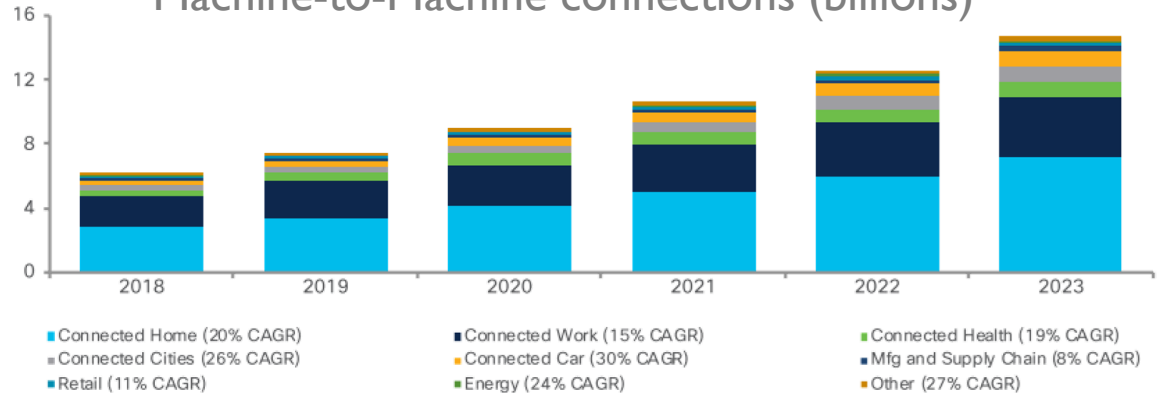


<https://development.libelium.com/smart-agriculture-xtreme-sensor-guide/>

Autonomous
Perpetual
Operation

- Millions of usage scenarios (deploy-and-forget)
- Massive scaling

Machine-to-Machine connections (billions)






Source: Cisco Annual Internet Report, 2018-2023

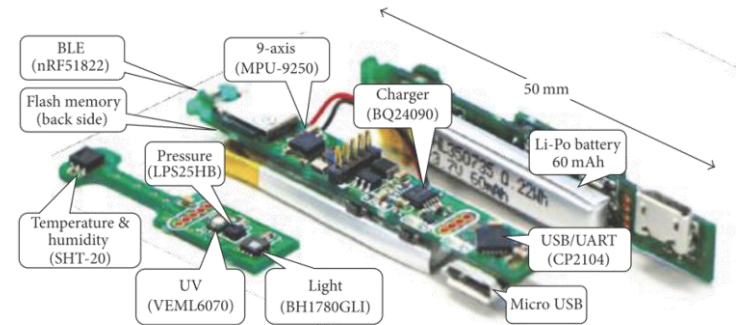
Energy Neutrality and multiple objectives

Energy Neutral Operation

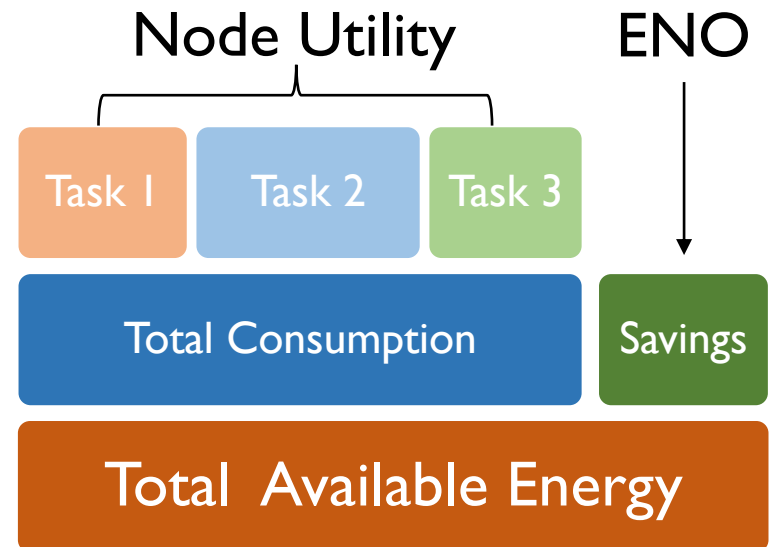
- Balancing energy generation and consumption

Modern EHWSNs are **multi-task**

- Sensing 
- Processing 
- Communication 
- Allocate energy among tasks
 - To maximize utility
 - According to user priority
 - Only known during runtime (not a priori)



[Nakamura et al 2017, SenStick: Comprehensive Sensing Platform with an Ultra Tiny All-In-One Sensor Board for IoT Research]



Optimizing over multiple objectives

- Use Multi-objective Reinforcement Learning (MORL) to learn the energy management policy

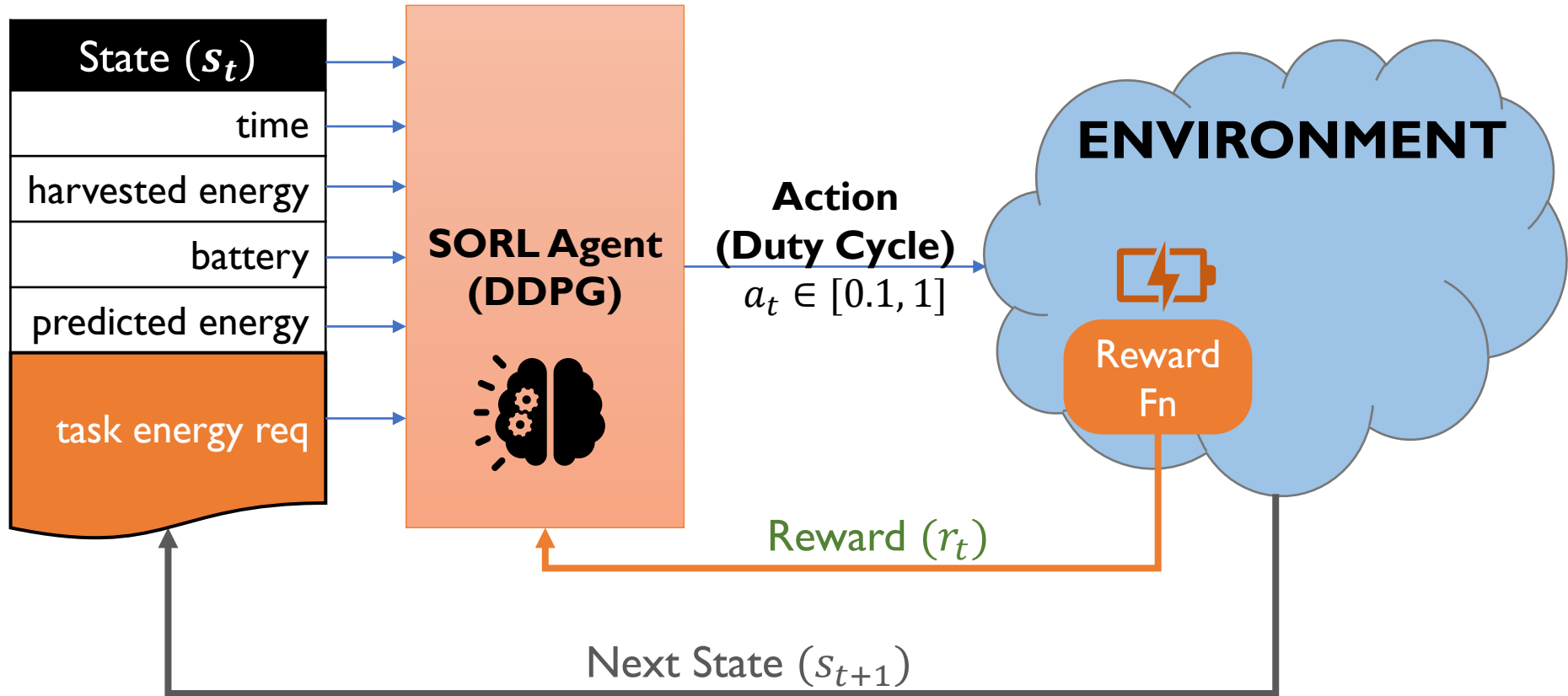
Proposal

- General Multi-Objective MDP Formulation
 - Continuous States and Actions
 - Single/Multiple rewards
- Novel low-compute MORL algorithms

Results

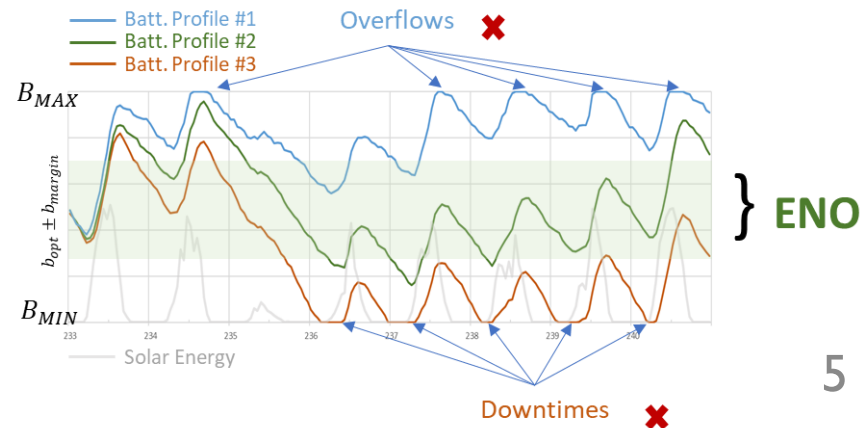
- Near-optimal policies
 - Better than scalarization methods
- Low learning costs
- Runtime Tradeoffs

Single-objective RL (SORL)

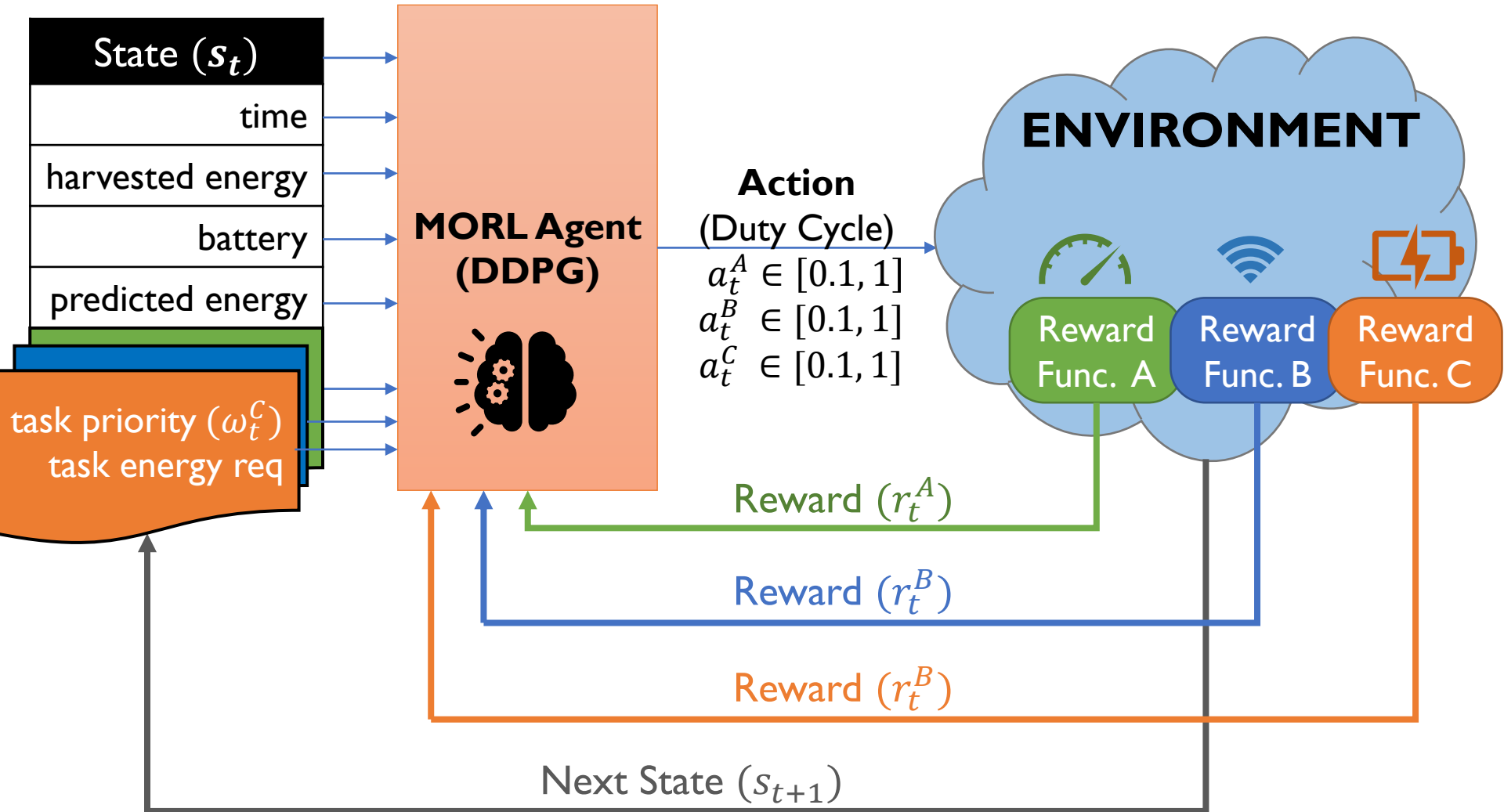


Shresthamali et. al., **Adaptive power management in solar energy harvesting sensor node using reinforcement learning**, EMSOFT 2017.

Shresthamali et. al., **Power Management of Wireless Sensor Nodes with Coordinated Distributed Reinforcement Learning**, ICCD 2019.



Multi-objective RL (MORL)



$$\text{Node utility, } w_t = \omega_t^A \times r_t^A + \omega_t^B \times r_t^B + \omega_t^C \times r_t^C$$



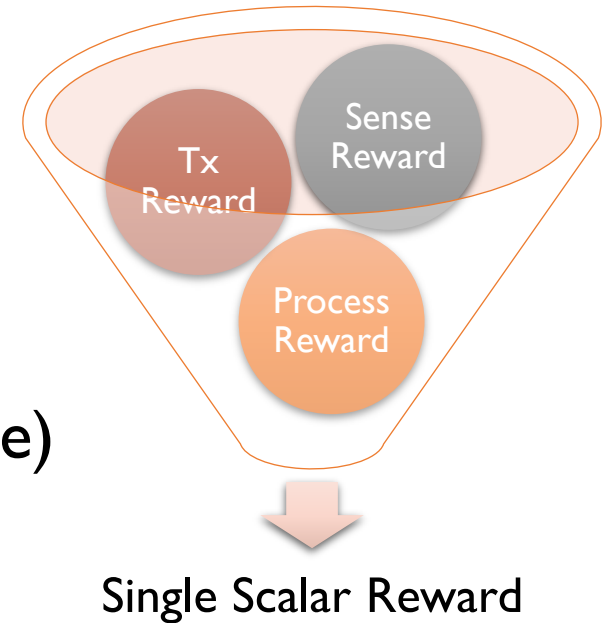
3. Optimizing over Multiple Objectives

Challenges of learning with many rewards

Scalarization

Mix rewards into one scalar

- *Aoudia et al., 2018:*
 - Multiply rewards together
 - Confounds rewards (noisy interference)
- *Ferreira et al., 2018:*
 - Add rewards together
 - Tradeoffs not possible
 - Prior knowledge of relative weights required
- *Hsu et al., 2014:*
 - Complicated unintuitive reward function
 - Unexpected behavior (reward hacking)



Proposed MORL Framework

1. General Multi-Objective MDP Formulation

- Rewards
 - Simpler, precise, intuitive rewards
 - Multiple sources of rewards (reward vector)
- States
 - Continuous
 - Inclusion of temporal information (more Markov)
- Actions
 - Continuous
 - Relative actions (Safe actions)

For efficient learning

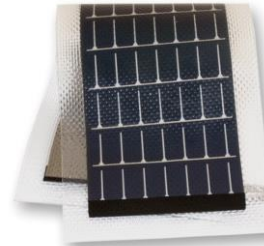
2. Low compute MORL algorithms (based on DDPG)

- Runtime MORL
 - Runtime tradeoffs using pre-learned greedy policies
- Off-policy MORL
 - Learn tradeoff policies from scratch with low learning costs

[Lillicrap et. al., 2015]

Simulation Parameters

Component	Rating
Battery (Rechargeable Li-Ion)	2000 mAh
Solar Panel	100 mA



Foldable Solar panel
(100 mA)



Li-Ion Battery
(2000mAh)

Device	Rating
Wasmote Sensor Platform ATmega1281 @15 MHz)	17 mA
Comm. Device (Zigbee 3)	40 mA
Sensor (GPS)	32 mA
TOTAL	89 ~ 100 mA



Wasmote

Parameter	maximum value	minimum value
Battery, b_t	b_{max}	$b_{min} = 10\%$ of b_{max}
Harvester, h_t	$h_{max} = 5\%$ of b_{max}	$h_{min} = 0$
EHWSN, z_t	$z_{max} = 5\%$ of b_{max}	$z_{min} = 0.5\%$ of b_{max}
Requests, d_t	$z_{max} = 5\%$ of b_{max}	$z_{min} = 0.5\%$ of b_{max}

Experimental Results

- Near-optimal Performance
 - Superior to scalarization methods

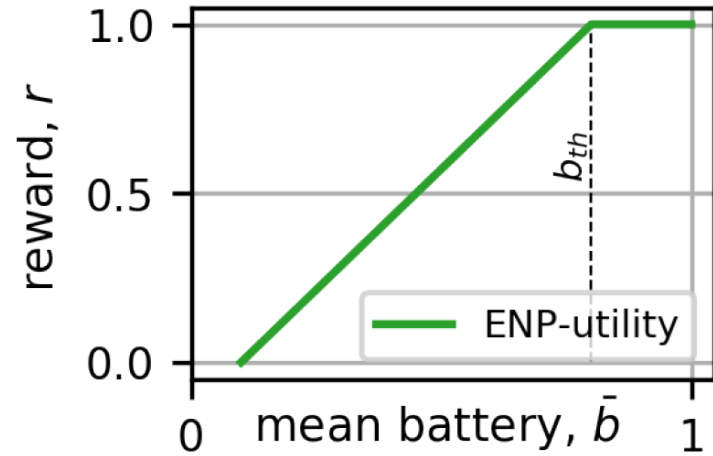
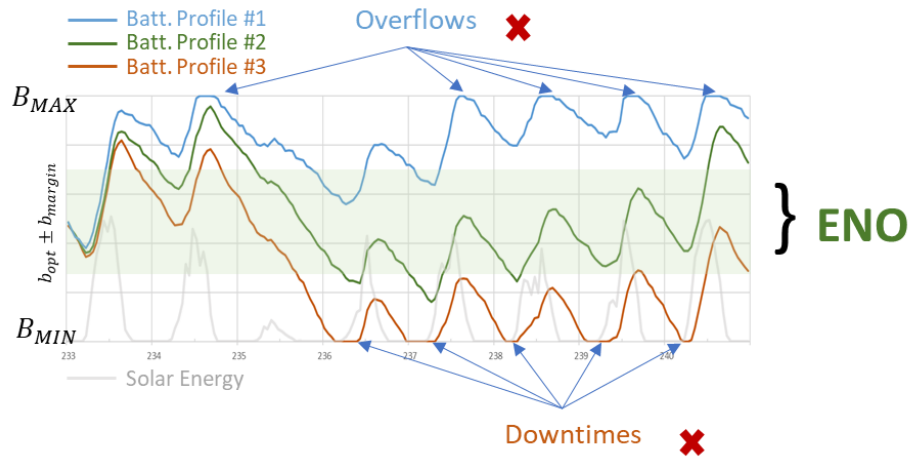


- Dynamic Runtime Tradeoffs

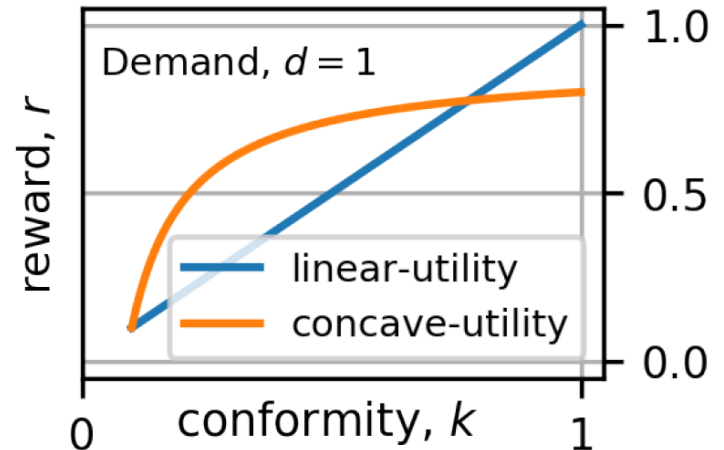
- Low learning cost
 - Safer Exploration
 - Faster learning

Multiple Objectives

Energy Neutral Performance (ENP)



Sensing and Transmission



Energy Scheduling

- At each timestep, the node allocates energy budget for
 - Sensing (w.r.t. user requirements)
 - Transmission (w.r.t. channel conditions)
- By taking the user-defined relative priority (ω) between
 - Sensing (ω_{sense})
 - Transmission (ω_{tx})
 - Energy-neutral performance (ω_{ENP})
- While ensuring long-term energy neutrality
 - Lower Downtimes = Better Energy Neutrality

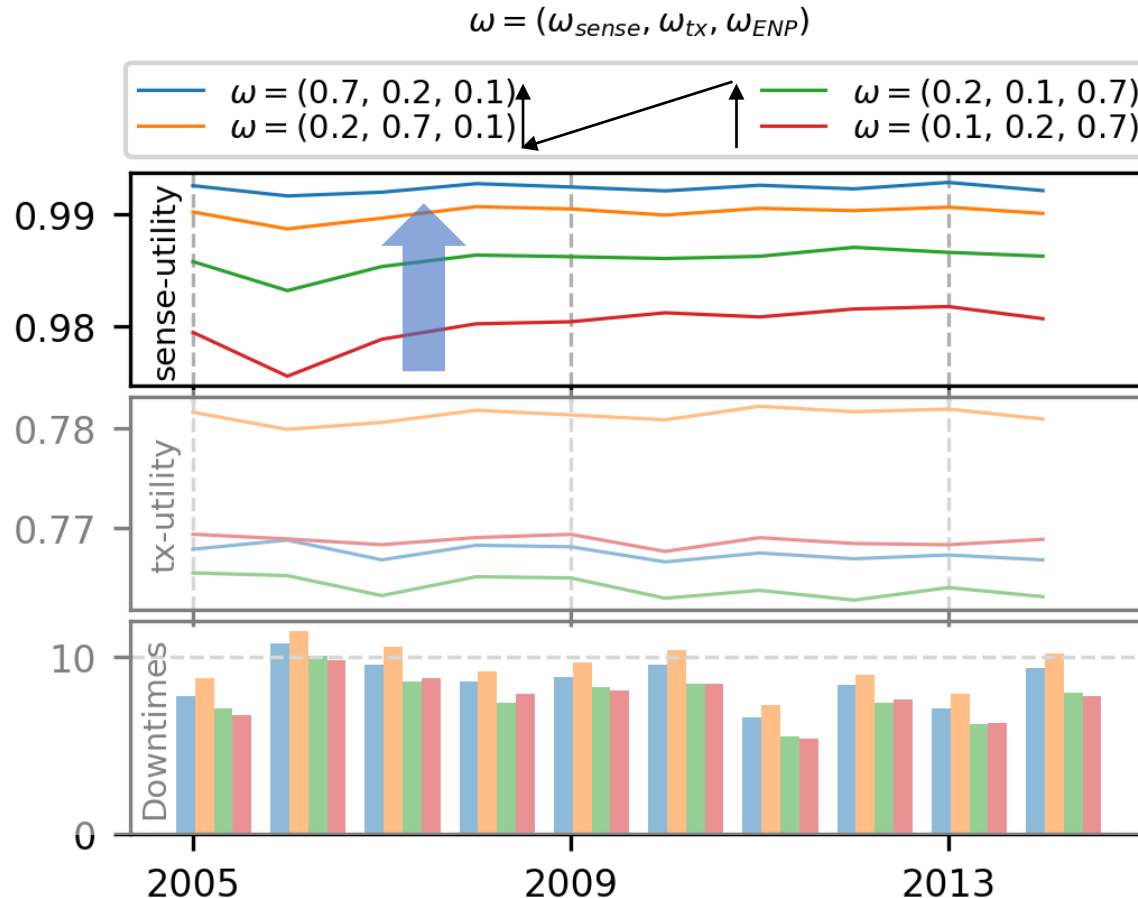
Runtime Tradeoffs (2-tasks)

Off-policy MORL Algorithm

- Tradeoff between sensing, transmission and energy-neutrality

Increasing ω_{sense} increases *sense-utility* correspondingly:

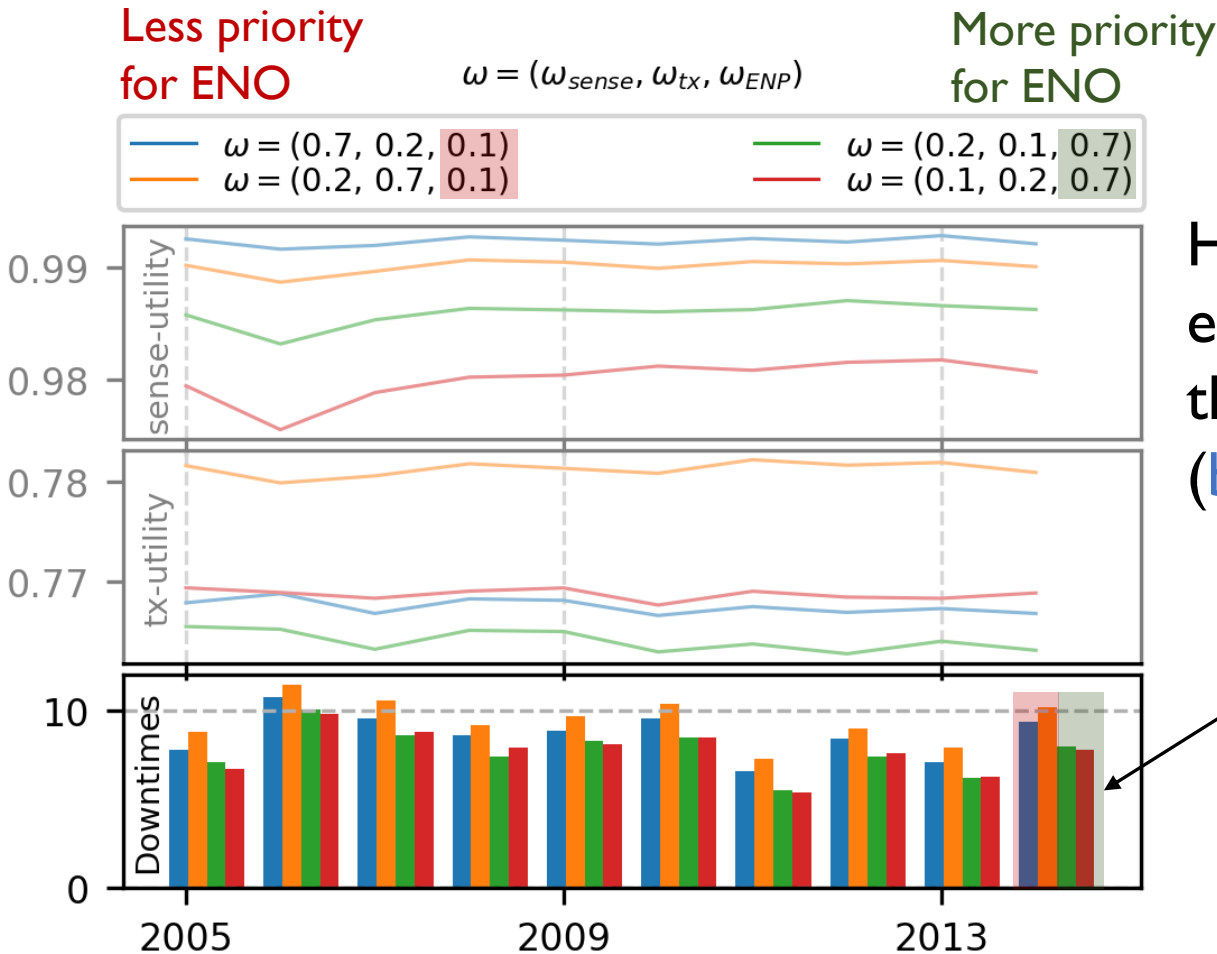
red → green → orange → blue



Runtime Tradeoffs (2-tasks)

Off-policy MORL Algorithm

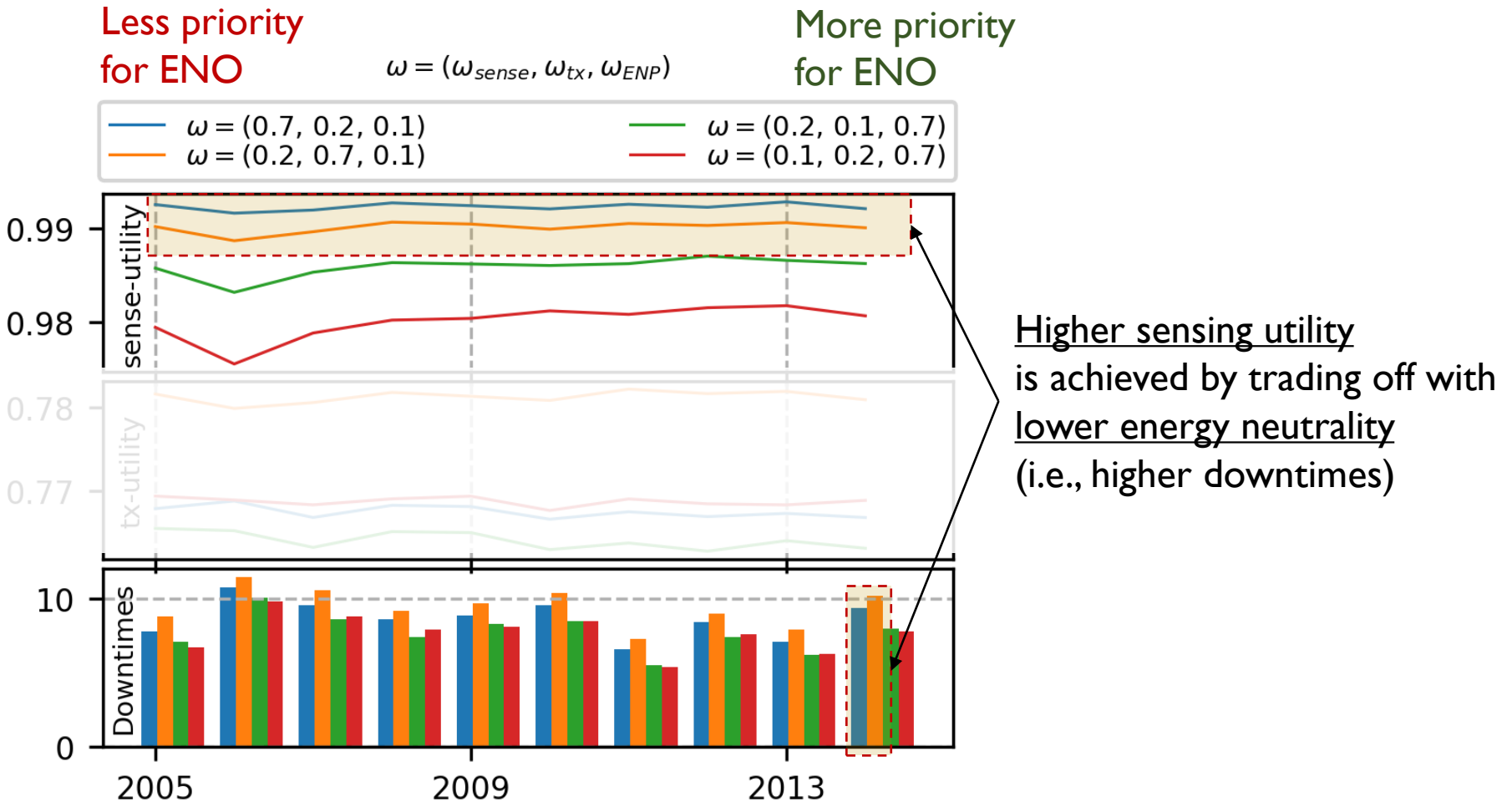
- Tradeoff between sensing, transmission and energy-neutrality
- $\omega = (\omega_{sense}, \omega_{tx}, \omega_{ENP})$



Runtime Tradeoffs (2-tasks)

Off-policy MORL Algorithm

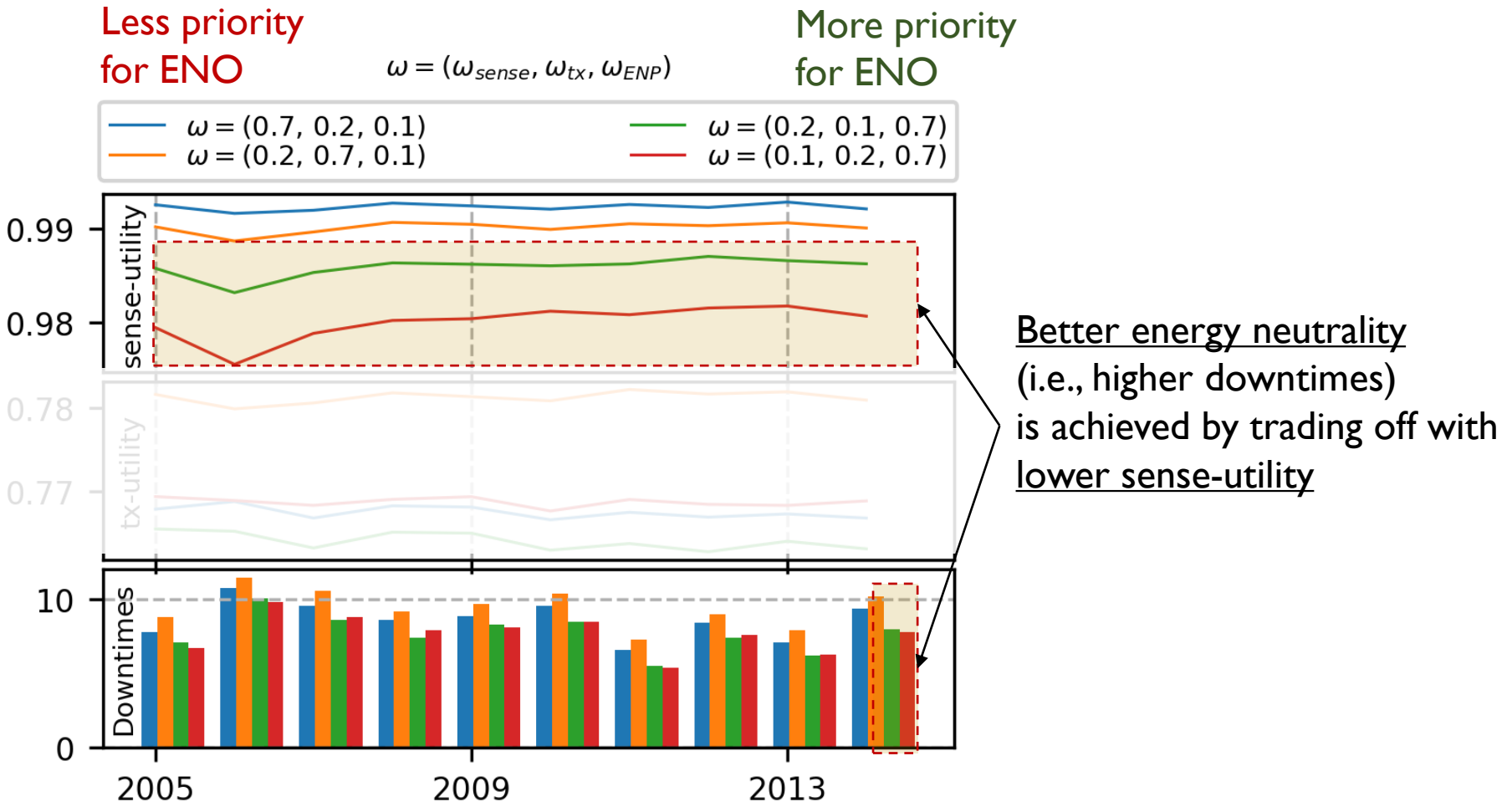
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Runtime Tradeoffs (2-tasks)

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Conclusion

- EHWSNs require RL based methods for
 - Adaptive, scalable policies
- RL is difficult for EHWSNs due to
 - Difficult problem formulation
 - High learning costs
 - High computation costs
 - **Multiple objective optimization problem**
- Traditional MDPs and scalarization methods
 - Are sub-optimal
 - Have high-learning costs
 - Cannot tradeoff
 - Require complicated reward functions
- Proposed MORL framework
 - Can learn near-optimal policies
 - With low learning costs
 - Can tradeoff at runtime
 - Simple/precise and diverse rewards can be used



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Japan Society for the Promotion of Science



Thank You

Your questions/comments and feedback are
most welcome